



ICAVE 2017

Singapore | September 1-3, 2017

2017 International Conference on
Automotive and Vehicle Engineering

2017年汽车和车辆工程国际会议

**2017 International Conference on Automotive and Vehicle Engineering (ICAVE2017)
Singapore, September 1-3, 2017**

Introduction

Welcome to the official website of the 2017 International Conference on Automotive and Vehicle Engineering (ICAVE2017). The conference will be held in Singapore during September 1-3, 2017. ICAVE2017 is a workshop of ICITE2016. The aim of ICAVE 2016 is to present the latest research and results of scientists related to Automotive and Vehicle Engineering topics. This conference provides opportunities for the different areas delegates to exchange new ideas and application experiences face to face, to establish business or research relations and to find global partners for future collaboration. We hope that the conference results constituted significant contribution to the knowledge in these up to date scientific field.

Keynote Speaker

Prof. Lee Der Horng

National University of Singapore, Singapore

Prof. Monteiro Figueira

University Lusofona, Portugal

Prof. Alan Nicholson

University of Canterbury, New Zealand

Prof. Susumu Hara

Nagoya University, Japan

Assoc. Prof. Tsuguo Nobe

Chief Advanced Service Architect and Director at Intel Corporation & Visiting Associate Professor at Nagoya University, Japan

Contacts

Ms. Annika N. Yang

Conference Secretary of ICAVE 2017

(1) Via Email: icave@zhconf.ac.cn

(2) Tel: +86-28-83533337

(AM 9:30-PM 18:00, Monday to Friday)

Important Date

Submission Deadline May 10th, 2017

Notification Date June 10th, 2017

Registration Deadline June 30th, 2017

Conference Dates September 1-3, 2017

Submission Methods

Please log in the **Electronic Submission System**; (.pdf only) to submit your full paper and abstract. For any inquiry about the conference, please feel free to contact us at: icave@zhconf.ac.cn

Call for Papers

- Advanced Driver Assistance Systems
- Automated Vehicles
- Active and Passive Vehicle Safety
- Vehicle Environment Perception
- Driver State and Intent Recognition
- Eco-driving and Energy-efficient Vehicles
- Impact on Traffic Flows
- Cooperative Vehicle-infrastructure Systems
- Collision Avoidance
- Pedestrian Protection
- V2X Communication
- Proximity Detection Technology
- Assistive Mobility Systems
- Proximity Awareness Technology
- Intelligent Ground, Air and Space Vehicles
- Autonomous / Intelligent Robotic Vehicles
- Image, Radar, Lidar Signal Processing
- Information Fusion
- Vehicle Control, etc